

Pedestrian Behaviour Modelling

An Application to Retail Movements using Genetic Algorithm

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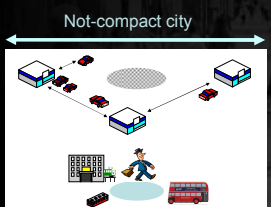
Background

- Urban planning
- Spatial marketing
- Location-based services


Background


- Urban planning

Not-compact city



Compact city





Lively town centres

Pedestrian-oriented planning

Background

- Pedestrian-oriented urban planning

- ✓ Safety less crime, fewer traffic accidents
- ✓ Convenience accessibility to transport, shops, services
- ✓ Amenity comfortable walking environment

Actual movements
Necessary information
Influential factors

➡ Needs for Pedestrian behavior model

Background

- Spatial marketing

- ✓ Tenant strategy (leasing, fee)
- ✓ Improvement of -floor plans
-signage system

Actual movements
Influential factors

➡ Needs for Pedestrian behaviour model



Background

- Location-based services
 - Provide appropriate information according to user's location / needs

3D-GIS

Positioning technology

trajectory

Routes for wheel chair user?

How to avoid traffic jam?

Where are my pals?

Patterns of users' routes/activities
Necessary Information - contexts

Needs for Pedestrian behavior model

Requirements of pedestrian behavior models

- There are several needs to develop pedestrian behaviour models
- Key issues
 - Understand and explain real pedestrian's movement
 - Represent dynamic interaction process between pedestrians and their environment (esp. Information which people obtain)

Requirements of pedestrian behavior models

Current spatial movement models

- Crowd dynamics
 - Micro scale behaviour (e.g. obstacle avoidance)
- Transport model
 - Network analysis and OD/route estimation
- Stochastic model
 - Probability of state-to-state transition

Crowd dynamics

Current position (x, y)
Velocity (u, v)
Radius r
Normal walking speed V_n
Destination (p_x, p_y) (q_x, q_y)
speed ratio k
Personal space ratio c
Information space (d, d')

↑ Estimation of the next steps of other pedestrians
← Collision avoidance behaviour

(Kai Botz)

Transport model

Area: S_1, S_2, \dots, S_n
Trips between S_1 to S_2, \dots, S_n
Distance between S_1 to S_2, \dots, S_n

Network analysis

(weights associated with each link can be distance, costs, condition of the road, etc)

- Influence of other areas?
- Which area generates more trips than others?
- Why?

Gravity model

$$y_{ij} = \alpha_i \beta_j e^{-\gamma d_{ij}}$$

α_i potential as origin
 β_j potential as destination

Most evacuation models adopt this concept

Crowd dynamics Ltd

Stochastic model

Home

Home (OD)

Place (node)

home

Trip 0

Trip 1

Trip 2

| Place | A | B | H | total |
|-------|-----|-----|-----|-------|
| A | 0 | 0.6 | 0.4 | 1 |
| B | 0.5 | 0 | 0.5 | 1 |
| H | 3 | 1 | 0 | |

Probability of visiting from one place to another

P_{ij}

The observed number of people at their first destination

F_{ij}

Probability of being the last destination

Number of people who visit each place via another (Trip $n: n > 1$)

$$RE = F_{HH}P_{HH} + F_{HH}P_{HH}^2 + \dots = F_{HH}P_{HH}(1 - P_{HH})^{-1}$$

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Requirements of pedestrian behavior models

| | advantage | disadvantage |
|--------------------|--|--|
| ✓ Crowd dynamics | <ul style="list-style-type: none"> Well represent micro-scale physical response Dynamic | Not take it into account: <ul style="list-style-type: none"> where they are going to and why pre-fixed route = static model geographical attributes |
| ✓ Transport model | <ul style="list-style-type: none"> Suitable for description of selection behavior | Several things can't be represented: <ul style="list-style-type: none"> interaction between others/environment cognitive process of pedestrian |
| ✓ Stochastic model | <ul style="list-style-type: none"> Useful for being briefed on how people move around Capable of representing changeability of movements | <ul style="list-style-type: none"> Inadequate to small scale movement Not explain why they choose certain place |

Understand and explain real pedestrian's movement

Represent dynamic interaction process between pedestrians and their environment

New pedestrian behaviour models are needed

Research Aim and Objectives

To develop a new pedestrian behavior model

- ✓ be capable of explaining real pedestrian's movement
 - Every factors should be determined based on observed data
 - It can deal with more complex behavior (e.g. shopping)
- ✓ represents dynamic interaction between pedestrians and their environment
 - To deal with not only pre-determined route-choice but also people's cognitive process or other changeable events
- ✓ can be used as a simulation model
 - To visualize, To make the model easy to understand, more transferable
- ✓ be validated through comparison between actual trajectories
 - It should be different from playing with beautiful animation

Framework of the model

Integrated Simulation Model of Pedestrian Movements

Built environment agents
 Geographic attributes
 Attraction level

Pedestrian agents
 Knowledge
 Needs

Multi-agent-based model

Interaction between environment

- collision avoidance
- walking speed
- basic walking tendencies (e.g. avoid rapid turn over)

Stimuli-Response

Calculation of the optimum route

- shortest path
- cognitive process
- spatial knowledge

Route choice

Matching between people's preference/needs and attributes of places

- Which place to be chosen as a destination?

Marketing

Framework of the model

3 levels of pedestrian's behavior

Stimuli-Response
 congestion, obstacle avoidance
 How they walk around?

Route choice
 Which route to take?
 Spatial knowledge, Environmental info, Attraction level

Marketing
 choose destinations
 Attraction level, Cost, Distance
 User's Attributes, Preference, Needs, Restriction

collecting information → New info → Records of Optimization choice

feedback

Methodology

- Stimuli-response**
 Survey of pedestrian movement in public spaces
 Measurement systems / sensors
 Trajectory → walking patterns
- Route choice**
 Surveys of route-choice behaviour
 Route A, Route B, Route G, DESTINATION
- Marketing**
 Marketing research
 Geo-demographic Database
 Develop DB of attributes of the place
 Analysis on relationship between the shop's attributes and those of individuals

Test Simulation

- Retail movement in a large shopping centre
 - Visitors have the same objective = Shopping
 - Survey area has distinct boundary
 - Shoppers "walk around"
- Shortest path model

START → Estimated route → Comparison → Real route

Planned destination


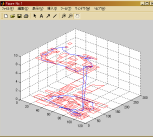
Typology of shoppers

| Type | Shop-till-you-drop consumer | | | middle | People who doesn't like to shop | |
|--------------------------|-----------------------------|-----------------------|---|---------------------------------|---|---|
| Category 1 | Shop explorer | | | Repeat guest (Regular customer) | Buying motives YES | Buying motives NO |
| Category 2 | Buying motives YES | Buying motives NO | Buying motives POTENTIAL | Shopping opportunity (Time) | | |
| Proposed critical factor | Satisfaction | information | Visibility of potential purchases | Fixed route | Visibility of potential purchases | Spatial knowledge |
| Route | | | | | | |
| Behaviour pattern | Complex Time: long | Try to see whole area | Shortest path & Other factors Time: long | Shortest path Time: long | Deviate from prefixed route by visual stimulus Time: short | Shortest path Time: short not go shopping |

Surveys of route choice behaviour

- Tracking retail movement
 - 18 samples (female, 20 year-old)
 - 2 hours shopping * 3 times
- Analysis on influential factors on shopper's route choice
 - ✓ Knowledge about the place
 - ✓ Time constraints
 - ✓ Preferences

Shop-till-you-drop consumer?
People who doesn't like to shop?

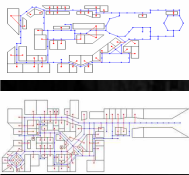




Test simulation using GA

Time resolution=30 seconds

Time: 0 1 2 3 4 5 ... chromosome

chromosome: A B C D E ...

shop network trajectory

326 nodes (shops, centre points of corridor-every 10m)
364 links (corridor)

Test simulation using GA

Evaluation criteria

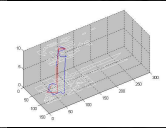
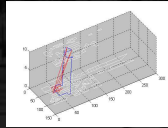
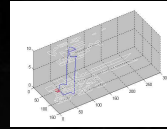
$$\max f = \sum_{i=1}^n a_i \cdot x_i$$

α Parameter
 x Evaluation function for criterion i

- Travel distances (the shortest-path model)
- Does it include the ID of nodes which were scheduled to visit?
- Prefixed Start point and Goal point
- Physical restriction
 - walking speed (average 60 metres per minute)
 - rotation angle (less than 150 degree)
 - limited vertical movements

Results

- calibration
 - Estimated route (red)
 - Observed route (blue)

Test simulation without restriction on distance with severe restriction on distance


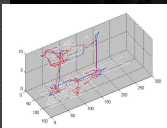
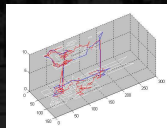
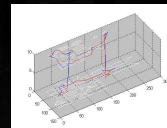
| | | |
|-----------------|-----------------|------|
| Evaluated value | Estimated route | 7.62 |
| | Observed route | 7.69 |

➔ Set weighted parameters' values

Results

Observed route (blue)

Estimated route (red)

Simulation 1 Simulation 2 Given the real route as one of initial chromosomes

| | | | | | | |
|---------------------------|-----------------|-------|-----------------|-------|-----------------|-------|
| Evaluated value | Estimated route | 100 | Estimated route | 99.5 | Estimated route | 108.8 |
| | Observed route | 107 | Observed route | 107 | Observed route | 107 |
| Distance between 2 routes | | 68.8m | | 52.4m | | 1.25m |

Conclusion

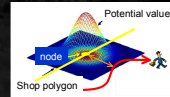
- Shortest path model
 - capable of predicting outlines of the routes
 - other influential factors
 - Evaluation criteria and parameter values tested

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Future research

✓ Improving the simulation system

- Combining network and potential distribution



Implement simulation

- Network analysis

→ factors in route selection
– width of corridor, visibility, connection to other network

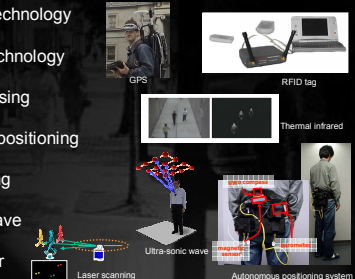
✓ Marketing research

- Develop DB of attributes of the place
- Analysis on relationship between the place's attributes and those of pedestrian
 - What kind of people go to WHICH place (shop/restaurant)
 - HOW often?
 - WHY?

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Current positioning technologies

- ✓ GPS-based technology
- ✓ Cell-based technology
- ✓ Image processing
- ✓ Autonomous-positioning
- ✓ Laser scanning
- ✓ Ultra-sonic wave
- ✓ Traffic counter



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Thank you!

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